# The Nullstellensatz for Sparse Tropical Polynomial Systems

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Wednesday, August 31st

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- The main classical tools for dealing with these questions are the theory of resultants and Macaulay matrices. In this work, we develop their tropical analog.
- Two main concerns: find the 'smallest' suitable witness and be able to deal with sparse systems.

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## 1 Tropical algebra and tropical polynomials

- Generalities on tropical algebra
- Tropical polynomials
- 2 Definitions and tools for the Nullstellensatz
  - Overview of the problem and the preexisting results
  - The Macaulay matrix
  - Newton polytopes
- 3 The Nullstellensatz for Sparse Tropical Polynomial Systems
  - Statement of the theorem
  - Outline of the proof
  - Further results

Generalities on tropical algebra Tropical polynomials

## • Tropical semiring $\mathbb{R}_{\infty} = \big(\mathbb{R} \cup \{-\infty\}, \oplus, \odot\big)$ with

- addition  $\oplus := \max$ ;
- multiplication  $\odot := +;$
- zero element  $\mathbb{0}:=-\infty$ ;
- unit element 1 := 0.

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- Satisfies the usual properties of a field except **no additive inverse**.
- Tropical operations can be extended to vectors and matrices with coefficients in  $\mathbb{R}_{\infty}$  allowing us to perform **tropical linear algebra**.

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Generalities on tropical algebra Tropical polynomials

#### • A formal tropical polynomial p in n variables is a map



such that  $p_{\alpha} \neq 0$  for finitely many  $\alpha \in \mathbb{Z}^n$ . We denote  $\rho = \bigoplus_{\alpha \in \mathbb{Z}^n} p_{\alpha} X^{\alpha}$ .

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• Support of p: supp $(p) := \{ \alpha \in \mathbb{Z}^n : p_\alpha \neq 0 \}$ 

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- Support of p: supp $(p) := \{ \alpha \in \mathbb{Z}^n : p_\alpha \neq 0 \}$
- Polynomial function associated to p:

$$\hat{p}: \left\{ egin{array}{ccc} \mathbb{R}^n & \longrightarrow & \mathbb{R}_\infty \ x & \longmapsto & \hat{p}(x) := \max_{lpha \in \mathcal{A}} (p_lpha + \langle x, lpha 
angle) 
ight.$$

with  $\mathcal{A} = \operatorname{supp}(p)$ 

Generalities on tropical algebra Tropical polynomials

#### Example: In the system

$$(E_1): \left\{ egin{array}{rll} f_1 &=& 1\oplus 2x_1\oplus 1x_2\oplus 1x_1x_2\ f_2 &=& 0\oplus 0x_1\oplus 1x_2\ f_3 &=& 2x_1\oplus 0x_2\ , \end{array} 
ight.$$

the polynomials have respective supports

$$\left\{ \begin{array}{rrrr} \mathcal{A}_1 &=& \{(0,0),(1,0),(0,1),(1,1)\}\\ \mathcal{A}_2 &=& \{(0,0),(1,0),(0,1)\}\\ \mathcal{A}_3 &=& \{(1,0),(0,1)\} \end{array} \right.$$

Same goes for the system

$$(E_2): \left\{ \begin{array}{rrrr} f_1 &=& 1 \oplus 4x_1 \oplus 1x_2 \oplus 3x_1x_2 \\ f_2 &=& 0 \oplus 0x_1 \oplus 1x_2 \\ f_3 &=& 2x_1 \oplus 0x_2 \end{array} \right.,$$

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Generalities on tropical algebra Tropical polynomials

•  $x \in \mathbb{R}_{\infty}^{n}$  is a **root** of a polynomial *p* whenever the maximum in the expression

$$\hat{p}(x) = igoplus_{lpha \in \mathcal{A}} p_lpha \odot x^{\odot lpha} = \max_{lpha \in \mathcal{A}} (p_lpha + \langle x, lpha 
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is attained twice. This is denoted as  $p(x) \nabla \mathbb{O}$ .

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is attained twice. This is denoted as  $p(x) \nabla \mathbb{O}$ .

•  $y \in \mathbb{R}^m$  is in the **tropical right null space** of a  $\ell \times m$  matrix  $A = (a_{ij})$  whenever for all  $1 \le i \le \ell$ , the maximum in the expression

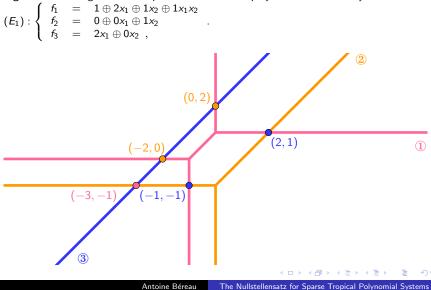
$$\bigoplus_{j=1}^m a_{ij} \odot y_j = \max_{1 \le j \le m} (a_{ij} + y_j)$$

is attained twice. This is denoted as  $A \odot y \nabla 0$ .

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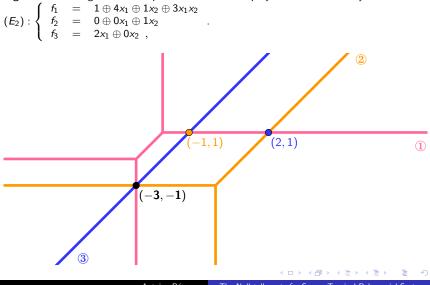
Generalities on tropical algebra Tropical polynomials

#### Figure: The arrangement of tropical varieties of the polynomials from the system



Generalities on tropical algebra Tropical polynomials

#### Figure: The arrangement of tropical varieties of the polynomials from the system



Antoine Béreau The Nullstellensatz for Sparse Tropical Polynomial Systems

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**Problem:** Decide whether there is a common tropical zero  $x \in \mathbb{R}^n$ , that is such that  $f_i(x) \nabla \mathbb{O}$  for all  $1 \le i \le n$ .

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*Remark:* The same question exists for solution in  $\mathbb{R}^n_{\infty}$ . It reduces to the  $\mathbb{R}^n$  by considering the supports.

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Overview of the problem and the preexisting results The Macaulay matrix Newton polytopes

#### Classically there two types of answers for this kind of questions:

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- Hilbert's Nullstellensätze

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Overview of the problem and the preexisting results The Macaulay matrix Newton polytopes

#### Let $\mathcal{A} = (\mathcal{A}_1, \dots, \mathcal{A}_k)$ be a collection of finite subsets of $\mathbb{Z}^n$ .

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$$\mathcal{W}_{\mathbb{K}}(\mathcal{A}) = \left\{ (f,x) \in \left( (\mathbb{K}^*)^{\mathcal{A}_1} imes \cdots imes (\mathbb{K}^*)^{\mathcal{A}_k} 
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Now consider  $\mathcal{Z}_{\mathbb{K}}(\mathcal{A})$  the projection of  $\mathcal{W}_{\mathbb{K}}(\mathcal{A})$  onto the first factor of the cartesian product, that is

$$\mathcal{Z}_{\mathbb{K}}(\mathcal{A}) = \left\{ f \in (\mathbb{K}^*)^{\mathcal{A}_1} \times \cdots \times (\mathbb{K}^*)^{\mathcal{A}_k} : \exists x \in (\mathbb{K}^*)^n, \ \forall i, f_i(x) = 0 \right\}.$$

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Then, we define the **resultant variety**  $\mathcal{RV}_{\mathbb{K}}(\mathcal{A})$  associated to  $\mathcal{A}$  as the Zariski closure  $\overline{\mathcal{Z}_{\mathbb{K}}(\mathcal{A})}$  of the previous set.

# Similarly, the tropical incidence variety associated to ${\mathcal A}$ is defined as the set

$$\mathcal{W}_{trop}(\mathcal{A}) = \left\{ (f, x) \in \left( \mathbb{R}^{\mathcal{A}_1} \times \cdots \times \mathbb{R}^{\mathcal{A}_k} \right) \times \mathbb{R}^n : \forall i, f_i(x) \nabla \mathbb{O} \right\},\$$

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Similarly, the tropical incidence variety associated to  ${\mathcal A}$  is defined as the set

$$\mathcal{W}_{trop}(\mathcal{A}) = \left\{ (f, x) \in \left( \mathbb{R}^{\mathcal{A}_1} \times \cdots \times \mathbb{R}^{\mathcal{A}_k} \right) \times \mathbb{R}^n : \forall i, f_i(x) \nabla \mathbb{O} \right\},$$

and the projection of  $\mathcal{W}_{trop}(\mathcal{A})$  on the first factor is the set

$$\mathcal{Z}_{\mathsf{trop}}(\mathcal{A}) = \left\{ f \in \mathbb{R}^{\mathcal{A}_1} \times \cdots \times \mathbb{R}^{\mathcal{A}_k} : \exists x \in \mathbb{R}^n, \ \forall i, f_i(x) \ \nabla \ \mathbb{O} \right\},\$$

but this time the **tropical resultant variety**  $\mathcal{RV}_{trop}(\mathcal{A})$  associated to  $\mathcal{A}$  is simply defined by  $\mathcal{RV}_{trop}(\mathcal{A}) = \mathcal{Z}_{trop}(\mathcal{A})$ .

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If k = n + 1 and if the resultant variety  $\mathcal{RV}_{\mathbb{K}}(\mathcal{A})$  is a hypersurface, *i.e.* that it is described by a single irreducible polynomial equation of the form  $\mathcal{R}(f) = 0$ , then we call the polynomial  $\mathcal{R}$  the **sparse resultant polynomial** of the family f.

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Moreover, if  $\mathcal{RV}_{\mathbb{K}}(\mathcal{A})$  is not a hypersurface, then the resultant is simply taken to be the constant polynomial equal to 1.

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Moreover, if  $\mathcal{RV}_{\mathbb{K}}(\mathcal{A})$  is not a hypersurface, then the resultant is simply taken to be the constant polynomial equal to 1.

The fact that  $\mathcal{RV}_{\mathbb{K}}(\mathcal{A})$  is an hypersurface can be characterized by a combinatorial condition on the collection of supports  $\mathcal{A}$ .

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Under the same assumptions, the **tropical resultant polynomial**  $\mathcal{R}_{trop}$  is defined as the support function of the Newton polytope of the classical resultant polynomial.

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$$\mathcal{R}_{ ext{trop}}(f) = igoplus_{
u \in M} f^
u \; ,$$

where M is the set of exponents of essential monomials of the classical resultant polynomial.

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Overview of the problem and the preexisting results The Macaulay matrix Newton polytopes

The theory of tropical resultant varieties was explored by Jensen and Yu (2013) who showed that the tropical resultant variety coincides with the tropicalisation of the classical resultant variety, following the work of Sturmfels (1994) and coauthors who characterized the Newton polytope of the classical resultant.

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From these results, we were able to show the following theorem:

#### Tropical resultant

Under the previous assumptions for k = n + 1, the following assertions are equivalent:

• There exists  $x \in \mathbb{R}^n$  such that  $f_i(x) \nabla 0$  for all  $1 \le i \le n+1$ ;

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$$\mathcal{R}_{trop}(f) \nabla \mathbb{0};$$

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Overview of the problem and the preexisting results **The Macaulay matrix** Newton polytopes

• **Nullstellensatz**: linearization method reducing the search of a solution of a polynomial system to the search of nonzero elements in the kernel of a matrix.

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- The Macaulay matrix associated to f is the (infinite) matrix  $\mathcal{M} = (m_{(i,\alpha),\beta})$  indexed by  $([n] \times \mathbb{Z}^n) \times \mathbb{Z}^n$ , where  $m_{(i,\alpha),\beta}$  corresponds to the coefficient of  $X^{\beta}$  in the polynomial  $X^{\alpha}f_i$ .

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- A finite subset \$\mathcal{E}\$ of \$\mathbb{Z}^n\$ yields a (finite) submatrix \$\mathcal{M}\_{\mathcal{E}}\$ of \$\mathcal{M}\$ obtained by taking only the rows whose support is included in \$\mathcal{E}\$ and the columns indexed by \$\mathcal{E}\$.

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- For  $\mathcal{E} = \{ \alpha \in \mathbb{N}^n : \alpha_1 + \dots + \alpha_n \leq N \}$ , we denote  $\mathcal{M}_N := \mathcal{M}_{\mathcal{E}}$ .

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A tropical Nullstellensatz was established by Grigoriev and Podolskii (2018) for full polynomials. It uses the submatrix  $\mathcal{M}_N$  of the Macaulay matrix  $\mathcal{M}$  obtained by truncating it to the degree  $N = (n+2)(d_1 + \cdots + d_k).$ 

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## Tropical Dual Nullstellensatz [Grigoriev and Podolskii (2018)]

The polynomials of f have a common root  $x \in \mathbb{R}^n$  iff there exists a vector  $y \in \mathbb{R}^m$  with  $m = \binom{N+n}{n}$  in the tropical right null space of the truncated Macaulay matrix  $\mathcal{M}_N$  for

$$N=(n+2)(d_1+\cdots+d_k) \ .$$

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Overview of the problem and the preexisting results **The Macaulay matrix** Newton polytopes

 The problem of finding a vector y ∈ ℝ<sup>n</sup> such that *M<sub>N</sub>* ⊙ y ∇ 0 can be solved using mean payoff games cf Akian, Gaubert and Guterman (2009).

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- However, the truncation degree of Grigoriev and Podolskii does not match the Macaulay degree in the classical theory which is equal to  $d_1 + \cdots + d_{n+1} n$  in the case k = n + 1.

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- However, the truncation degree of Grigoriev and Podolskii does not match the Macaulay degree in the classical theory which is equal to  $d_1 + \cdots + d_{n+1} n$  in the case k = n + 1. Their proof did not seem to allow room for improving this bound.

This work improves on Grigoriev and Podolskii's result by taking into account the sparse structure of the polynomials, and connects the tropical Nullstellensatz with classical elimination theory. In particular, it relies on a construction by Canny and Emiris (1993) and Strumfels (1994).

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This result in an improved truncation degree and allows us to deal better with sparse polynomials.

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## • For $1 \le i \le k$ , $Q_i := \operatorname{conv}(\mathcal{A}_i)$ is the **Newton polytope** of $f_i$ .

Antoine Béreau The Nullstellensatz for Sparse Tropical Polynomial Systems

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Introduction and motivation Tropical algebra and tropical polynomials Definitions and tools for the Nullstellensatz The Nullstellensatz for Sparse Tropical Polynomial Systems	Overview of the problem and the preexisting results The Macaulay matrix <b>Newton polytopes</b>
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- For  $1 \le i \le k$ ,  $Q_i := \operatorname{conv}(\mathcal{A}_i)$  is the **Newton polytope** of  $f_i$ .
- The upper hull of the lifted support {(α, f<sub>i,α</sub>) : α ∈ A<sub>i</sub>} is the graph of a function h<sub>i</sub> with support Q<sub>i</sub>.

Introduction and motivation Tropical algebra and tropical polynomials Definitions and tools for the Nullstellensatz The Nullstellensatz for Sparse Tropical Polynomial Systems	Overview of the problem and the preexisting results The Macaulay matrix <b>Newton polytopes</b>
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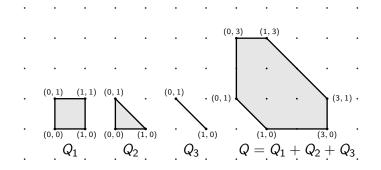
- For  $1 \le i \le k$ ,  $Q_i := \operatorname{conv}(\mathcal{A}_i)$  is the **Newton polytope** of  $f_i$ .
- The upper hull of the lifted support {(α, f<sub>i,α</sub>) : α ∈ A<sub>i</sub>} is the graph of a function h<sub>i</sub> with support Q<sub>i</sub>.
- If h := h₁ □ · · · □ h<sub>k</sub> where □ denotes the sup-convolution, then hypo(h) = hypo(h₁) + · · · + hypo(h<sub>k</sub>) and moreover the supports of h is Q = Q₁ + · · · + Q<sub>k</sub>.

Introduction and motivation Tropical algebra and tropical polynomials Definitions and tools for the Nullstellensatz The Nullstellensatz for Sparse Tropical Polynomial Systems	Overview of the problem and the preexisting results The Macaulay matrix Newton polytopes
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- The projection of hypo(*h*) onto *Q* yields a **coherent mixed subdivision** of *Q*.

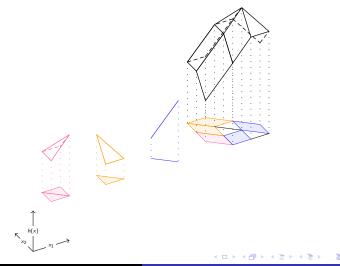
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The Newton polytopes associated to both systems  $(E_1)$  and  $(E_2)$  and their Minkowski sum are as follow.



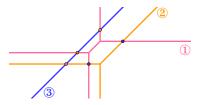
Overview of the problem and the preexisting results The Macaulay matrix **Vewton polytopes** 

**Figure:** The subdivision of *Q* associated to  $(E_1)$  arises from the projection of the Minkowski sum of the hypographs of the  $h_i$ .

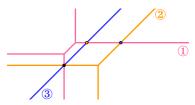


Overview of the problem and the preexisting results The Macaulay matrix Newton polytopes

(a) The arrangement of tropical varieties of the polynomials from the system  $(E_1)$ .



(c) The arrangement of tropical varieties of the polynomials from the system  $(E_2)$ .



(b) The subdivision of Q associated to  $(E_1)$ .



(d) The subdivision of Q associated to  $(E_2)$ .



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Antoine Béreau The Nullstellensatz for Sparse Tropical Polynomial Systems

Statement of the theorem Outline of the proof Further results

**Canny-Emiris set** associated to  $f: \mathcal{E} = (Q + \delta) \cap \mathbb{Z}^n$  with  $\delta$  a generic vector in the linear space directing the affine hull of Q.

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**Canny-Emiris set** associated to  $f: \mathcal{E} = (Q + \delta) \cap \mathbb{Z}^n$  with  $\delta$  a generic vector in the linear space directing the affine hull of Q. **Example:** Considering again the systems  $(E_1)$  and  $(E_2)$ , for

$$\delta = (-1 + \varepsilon, -1 + \varepsilon)$$

with  $\varepsilon > 0$  sufficiently small, we obtain the Canny-Emiris set

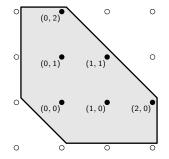
$$\mathcal{E} := (Q + \delta) \cap \mathbb{Z}^n = \{(0,0), (1,0), (0,1), (2,0), (1,1), (0,2)\}$$

corresponding to the set of monomials  $\{1, x_1, x_2, x_1^2, x_1x_2, x_2^2\}$ .

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Figure: The polytope 
$$Q + \delta$$
 with  $\delta = (-0.9, -0.9)$ .



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Statement of the theorem Outline of the proof Further results

## Nullstellensatz for Sparse Tropical Polynomial Systems

The system  $f \nabla 0$  has a solution  $x \in \mathbb{R}^n$  iff there exists a vector  $y \in \mathbb{R}^{\mathcal{E}'}$  in the tropical right null space of the submatrix  $\mathcal{M}_{\mathcal{E}'}$  of  $\mathcal{M}$ , where  $\mathcal{E}'$  is any subset of  $\mathbb{Z}^n$  containing a nonempty Canny-Emiris set  $\mathcal{E}$ .

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Statement of the theorem Outline of the proof Further results

## Nullstellensatz for Sparse Tropical Polynomial Systems

The system  $f \nabla \mathbb{O}$  has a solution  $x \in \mathbb{R}^n$  iff there exists a vector  $y \in \mathbb{R}^{\mathcal{E}'}$  in the tropical right null space of the submatrix  $\mathcal{M}_{\mathcal{E}'}$  of  $\mathcal{M}$ , where  $\mathcal{E}'$  is any subset of  $\mathbb{Z}^n$  containing a nonempty Canny-Emiris set  $\mathcal{E}$ .

**Corollary:** The system  $f \nabla 0$  has a solution  $x \in \mathbb{R}^n$  if and only if the truncated Macaulay tropical linear system  $\mathcal{M}_N \odot y \nabla 0$  has a solution  $y \in \mathbb{R}^m$  for

$$N=d_1+\cdots+d_k \ ,$$

where  $d_i = \deg(f_i)$  for all  $1 \le i \le k$ .

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**Example:** The matrix associated with system  $(E_1)$  is

There is no finite vector in its tropical right null space and thus there is no finite solution to the equation  $f \nabla \mathbb{O}$ .

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Statement of the theorem Outline of the proof Further results

**Example:** The matrix associated with system  $(E_2)$  is

The vector y = ver(-3, -1) = (0, -3, -1, -6, -4, -2) is finite and is in the tropical right null space of the previous matrix, hence there is a finite solution to the equation  $f \nabla \mathbb{O}$ , which is indeed given by (-3, -1).

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Statement of the theorem Outline of the proof Further results

A  $d \times d$  tropical matrix  $A = (a_{ij})_{1 \le i,j \le d}$  is tropically diagonally dominant whenever

 $a_{ii} > a_{ij}$ 

for all  $1 \le i, j \le d$  such that  $i \ne j$ .

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**Lemma:** If A is tropically diagonally dominant, then the only solution  $y \in \mathbb{R}^d_{\infty}$  to the equation  $A \odot y \nabla \mathbb{O}$  is  $y = \mathbb{O}$ .

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Statement of the theorem Outline of the proof Further results

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**Lemma:** If A is tropically diagonally dominant, then the only solution  $y \in \mathbb{R}^d_{\infty}$  to the equation  $A \odot y \nabla \mathbb{O}$  is  $y = \mathbb{O}$ .

*Proof:* Consider  $y_i = \max_{1 \le j \le n} y_j$ , then if  $y_i > -\infty$  then the inequalities  $a_{ii} > a_{ij}$  and  $y_i \ge y_j$  imply that

 $a_{ii} + y_i > a_{ij} + y_j$  for all  $1 \le i \ne j \le n$ ,

thus contradicting the assumption that  $A \odot y \nabla 0$ .

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 If f ∇ 0 has a solution x ∈ ℝ<sup>n</sup>, then the Veronese embedding y = ver(x) := (x<sup>p</sup>)<sub>p∈E'</sub> of x is a solution to M<sub>E'</sub> ⊙ y ∇ 0.

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- If f ∇ 0 has a solution x ∈ ℝ<sup>n</sup>, then the Veronese embedding y = ver(x) := (x<sup>p</sup>)<sub>p∈E'</sub> of x is a solution to M<sub>E'</sub> ⊙ y ∇ 0.
- Otherwise we apply a construction from Canny and Emiris (1993) and Sturmfels (1994) but in a potentially **non generic** case to show that there is no finite vector  $y \in \mathbb{R}^{\mathcal{E}'}$  in the tropical right null space of  $\mathcal{M}_{\mathcal{E}'}$ .

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If p ∈ E, then (p − δ, h(p − δ)) is in the relative interior of a facet F of hypo(h), and F can be written as F<sub>1</sub> + · · · + F<sub>k</sub> with F<sub>i</sub> faces of hypo(h<sub>i</sub>).

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- If p ∈ E, then (p − δ, h(p − δ)) is in the relative interior of a facet F of hypo(h), and F can be written as F<sub>1</sub> + · · · + F<sub>k</sub> with F<sub>i</sub> faces of hypo(h<sub>i</sub>).
- Since f does not have a common root, at least one F<sub>i</sub> is a singleton. Consider the maximal index j such that F<sub>j</sub> = {a<sub>j</sub>} is a singleton. The couple (j, a<sub>i</sub>) is called the row content of p.

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- If p ∈ E and if (j, a<sub>j</sub>) is its row content, then the support of the polynomial X<sup>p-a<sub>j</sub></sup>f<sub>j</sub> is included in E. This allows us to construct a square submatrix M<sub>EE</sub> = (m<sub>pp'</sub>)<sub>(p,p')∈E×E</sub> of M<sub>E</sub>.

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Statement of the theorem Outline of the proof Further results

• The matrix 
$$\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}} = (\widetilde{m}_{pp'})_{(p,p')\in\mathcal{E}\times\mathcal{E}}$$
 obtained by setting  $\widetilde{m}_{pp'} = m_{pp'} - h(p' - \delta)$  is tropically diagonally dominant.

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- The matrix  $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}} = (\widetilde{m}_{pp'})_{(p,p')\in\mathcal{E}\times\mathcal{E}}$  obtained by setting  $\widetilde{m}_{pp'} = m_{pp'} h(p' \delta)$  is tropically diagonally dominant.
- Therefore its tropical right null space is reduced to  $\{0\}$ , and thus this is also the case for  $\mathcal{M}_{\mathcal{EE}}$ .

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- Therefore its tropical right null space is reduced to  $\{0\}$ , and thus this is also the case for  $\mathcal{M}_{\mathcal{EE}}$ .
- Hence there does not exist  $y \in \mathbb{R}^{\mathcal{E}}$  such that  $\mathcal{M}_{\mathcal{E}} \odot y \nabla 0$ .

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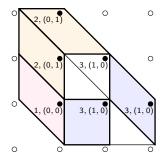
- The matrix  $\widetilde{\mathcal{M}}_{\mathcal{E}\mathcal{E}} = (\widetilde{m}_{pp'})_{(p,p')\in\mathcal{E}\times\mathcal{E}}$  obtained by setting  $\widetilde{m}_{pp'} = m_{pp'} h(p' \delta)$  is tropically diagonally dominant.
- Therefore its tropical right null space is reduced to {0}, and thus this is also the case for  $\mathcal{M}_{\mathcal{E}\mathcal{E}}$ .
- Hence there does not exist  $y \in \mathbb{R}^{\mathcal{E}}$  such that  $\mathcal{M}_{\mathcal{E}} \odot y \nabla 0$ .
- Finally, since  $\mathcal{M}_{\mathcal{E}'}$  can be written by block as

$$\mathcal{M}_{\mathcal{E}'} = \begin{pmatrix} \mathcal{E} & \mathcal{E}' \setminus \mathcal{E} \\ \mathcal{M}_{\mathcal{E}} & \mathbb{0} \\ * & * \end{pmatrix},$$

we deduce that there does also not exist  $y \in \mathbb{R}^{\mathcal{E}'}$  such that  $\mathcal{M}_{\mathcal{E}'} \odot y \nabla \mathbb{O}$ .

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**Figure:** The polytope  $Q + \delta$ , with interior integer points labelled by the row content of the cell they belong to for system ( $E_1$ ).



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Statement of the theorem Outline of the proof Further results

## For the system $(E_1)$ , we obtain the matrix

which is nonsingular.

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## *Proof of the corollary:* Take $\mathcal{E}'$ to be the simplex

 $\{\alpha \in \mathbb{N}^n : \alpha_1 + \cdots + \alpha_k \leq N\}$ .

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Statement of the theorem Outline of the proof Further results

*Proof of the corollary:* Take  $\mathcal{E}'$  to be the simplex

$$\{\alpha \in \mathbb{N}^n : \alpha_1 + \dots + \alpha_k \leq N\}$$
.

Remarks:

• This value of  $N = d_1 + \cdots + d_k$  improves on Grigoriev and Podolskii's result (2018) which gave

$$N=(n+2)(d_1+\cdots+d_k) \ .$$

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Moreover, the general theorem also allows to tackle the sparse case.

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Statement of the theorem Outline of the proof Further results

*Proof of the corollary:* Take  $\mathcal{E}'$  to be the simplex

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Remarks:

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$$N=(n+2)(d_1+\cdots+d_k)$$
.

Moreover, the general theorem also allows to tackle the sparse case.

• In most cases, we can even obtain the bound  $N = d_1 + \cdots + d_k - (k-1)$  which corresponds to the bound in the usual polynomial case.

**Bipartite systems** 
$$f^+ \ge f^-$$
 or  $f^+ = f^-$  with  $f^{\pm} = (f_1^{\pm}, \dots, f_k^{\pm})$ , *i.e.*

$$f_i^+(x) \ge f_i^-(x)$$
 for all  $1 \le i \le k$ 

or

$$f_i^+(x) = f_i^-(x)$$
 for all  $1 \le i \le k$ .

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$$f_i^+(x) = f_i^-(x)$$
 for all  $1 \le i \le k$ .

For  $f^+ \ge f^-$ , if  $f^-$  has a 'small' number of monomials, then the inequality can be reduced to the case where all polynomials  $f_i^-$  are monomials.

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In the case where all polynomials  $f_i^-$  are monomials, we consider  $f = f^+ \oplus f^-$  and we apply the previous construction to f in order to get a Canny-Emiris set  $\mathcal{E}$ .

Statement of the theorem Outline of the proof Further results

In the case where all polynomials  $f_i^-$  are monomials, we consider  $f = f^+ \oplus f^-$  and we apply the previous construction to f in order to get a Canny-Emiris set  $\mathcal{E}$ . We then have the following result:

## Positivstellensatz for Sparse Systems of Tropical Polynomials

There exists a solution  $x \in \mathbb{R}^n$  to the inequation  $f^+ \ge f^-$  if and only if there exists a vector  $y \in \mathbb{R}^{\mathcal{E}'}$  satisfying the inequality  $\mathcal{M}^+_{\mathcal{E}'} \odot y \ge \mathcal{M}^-_{\mathcal{E}'} \odot y$ , where  $\mathcal{E}'$  is any subset of  $\mathbb{Z}^n$  containing a nonempty Canny-Emiris subset  $\mathcal{E}$  of  $\mathbb{Z}^n$  associated to the system  $f^+ \ge f^-$ .

In the case where there are too many monomials, we apply the Canny-Emiris construction to (n + 1)Q instead of Q and use the Shapley-Folkman theorem in order to define the notion of row content in this case.

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Further results

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Work in progress or incoming :

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Unify these two cases;

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Further results

In the case where there are too many monomials, we apply the Canny-Emiris construction to (n + 1)Q instead of Q and use the Shapley-Folkman theorem in order to define the notion of row content in this case.

Work in progress or incoming :

- Unify these two cases;
- Tackle the case  $f^+ = f^-$ :

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In the case where there are too many monomials, we apply the Canny-Emiris construction to (n + 1)Q instead of Q and use the Shapley-Folkman theorem in order to define the notion of row content in this case.

Work in progress or incoming :

- Unify these two cases;
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- Develop eigenvalue methods to solve effectively tropical polynomial systems.

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## Thank you for your attention!

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